



**IEEE**

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# Organic Bio-Electronics: Health Care & Soft Robotics

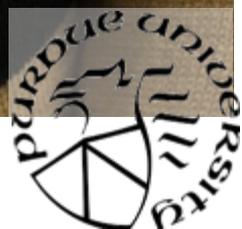
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**Purdue University**



**東京大学**  
THE UNIVERSITY OF TOKYO

**PURDUE**  
POLYTECHNIC





# BACKGROUND

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- Health monitoring equipment is getting smaller
- We want more comfortable, less obstructive monitoring
- Closer sensing to source of signal → higher SNR
- **Deployment on skin is desired** (to minimize stress and patient discomfort, and to maximize signal fidelity)

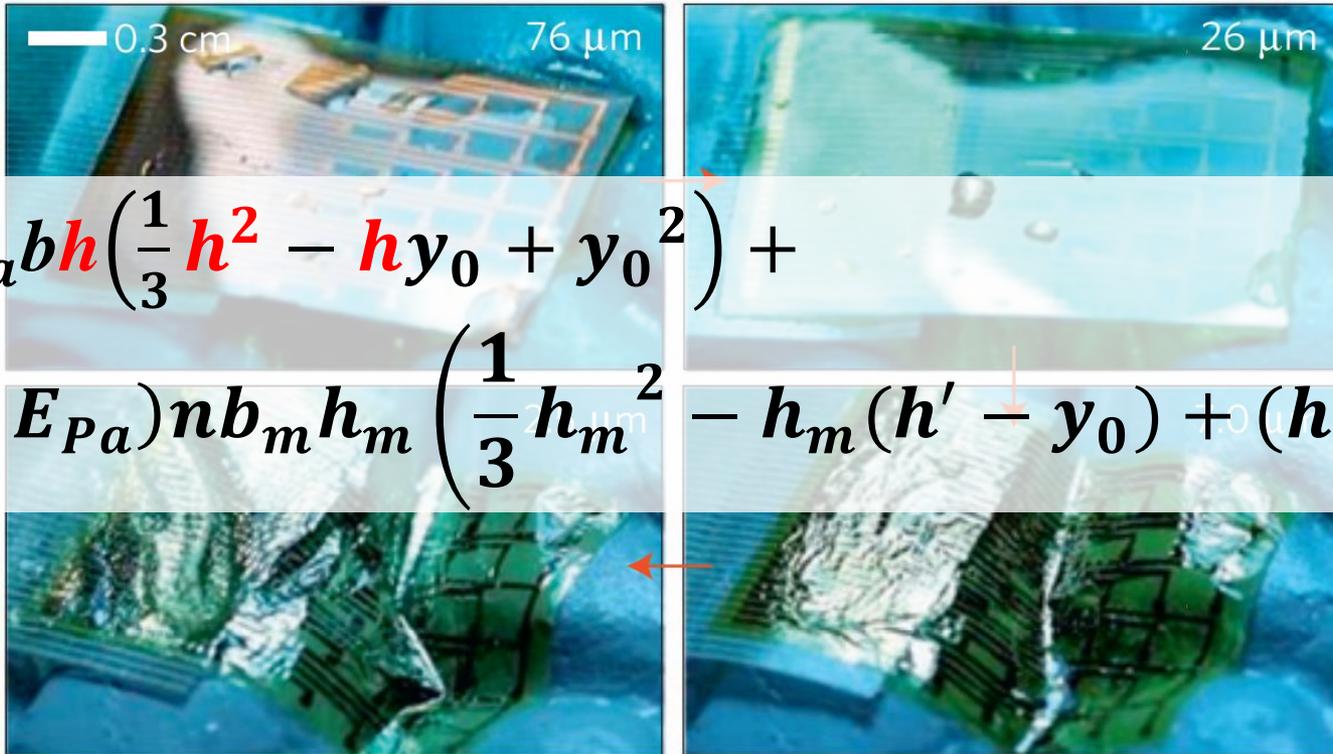




# BENDING STIFFNESS

3

- On-skin deployment requires electronics to be **ultra-thin, conformal, flexible, and biocompatible**<sup>1</sup>
- Bending stiffness** (radius)  $\propto$  film **thickness cubed**<sup>2</sup>



$$EI = E_{Pa} b h \left( \frac{1}{3} h^2 - h y_0 + y_0^2 \right) + (E_{Au} - E_{Pa}) n b_m h_m \left( \frac{1}{3} h_m^2 - h_m (h' - y_0) + (h' - y_0)^2 \right)$$



[1] M. Irimia-Vladu, *et al.*, *Adv. Funct. Mater.* **20**, 4069 (2010).

[2] D.-H Kim, *et al.*, *Nature Mat.* **9**, 511 (2010).

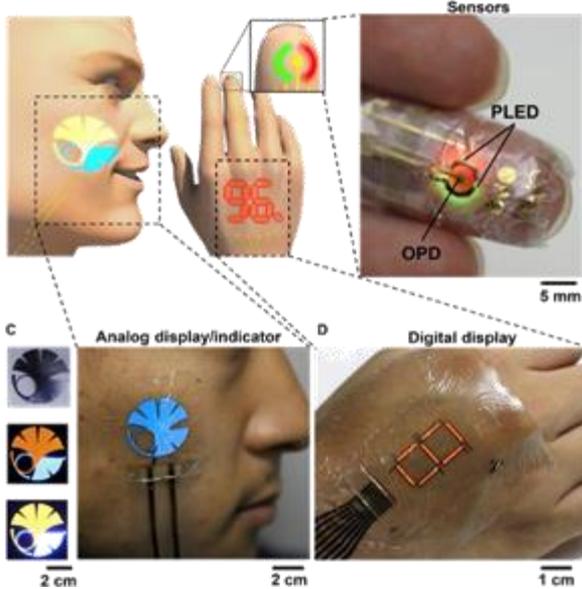




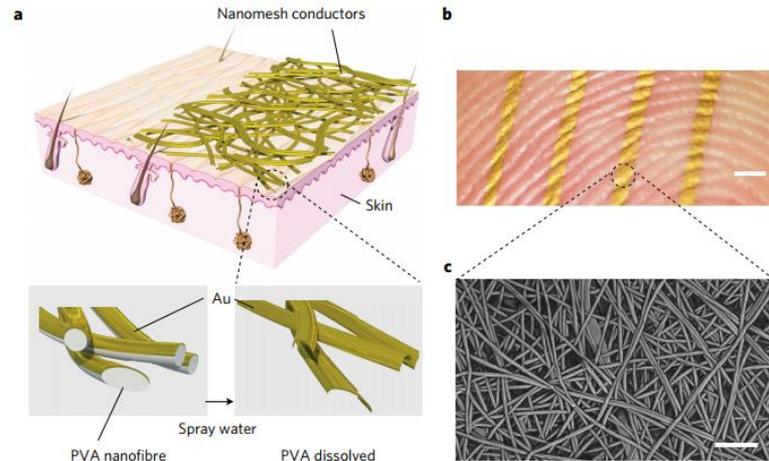
# SKIN THIN ELECTRONICS

4

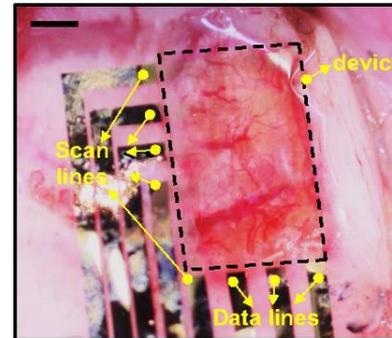
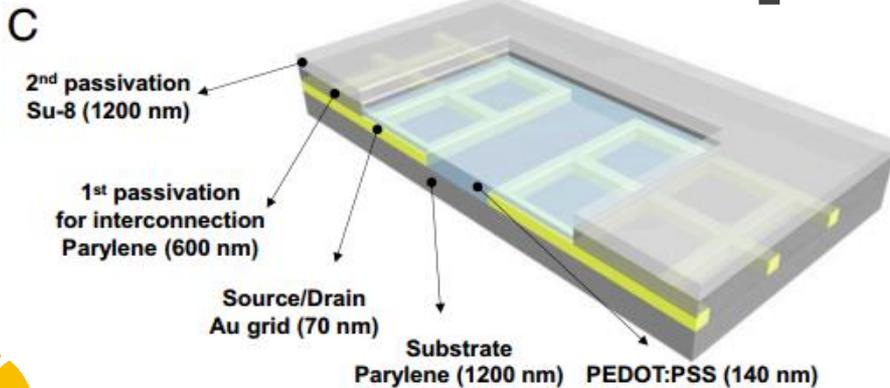
## Photonic skin<sup>3</sup>



## Mesh Electronics<sup>4</sup>



## Transparent OECTs<sup>5</sup>



[3] Yokota, *et al.*, Science Advances, 2, 4 (2016).

[4] Miyamoto, *et al.*, Nat. Nano, 12, 907-913 (2017).

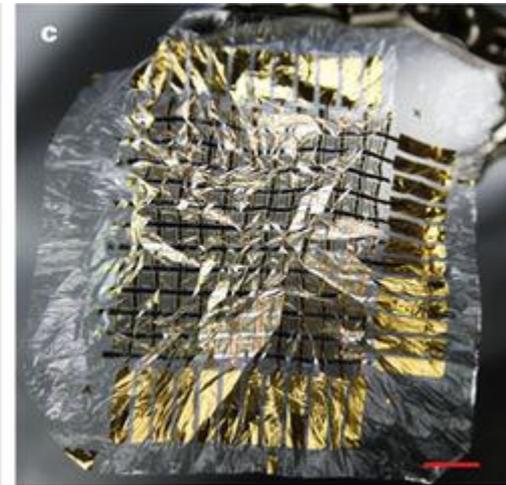
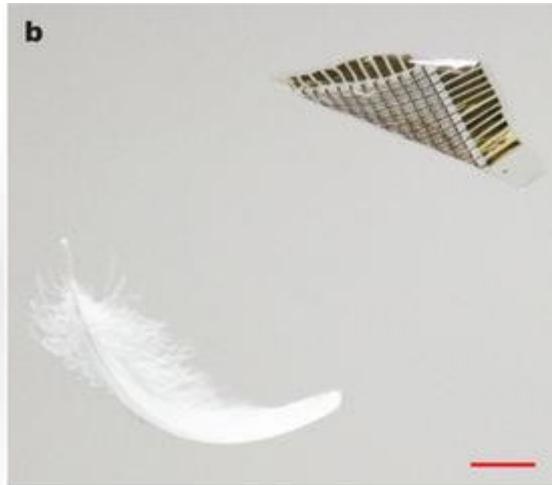
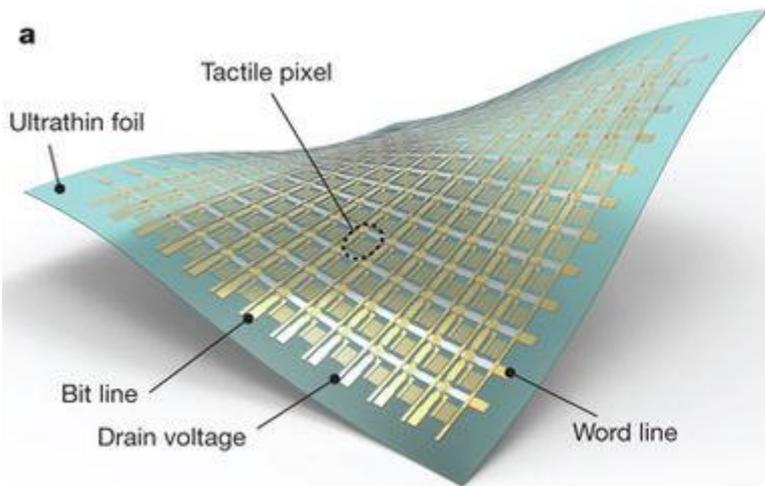
[5] Lee, *et al.*, PNAS 114, 40 (2017).





# BIO-ELECTRONICS

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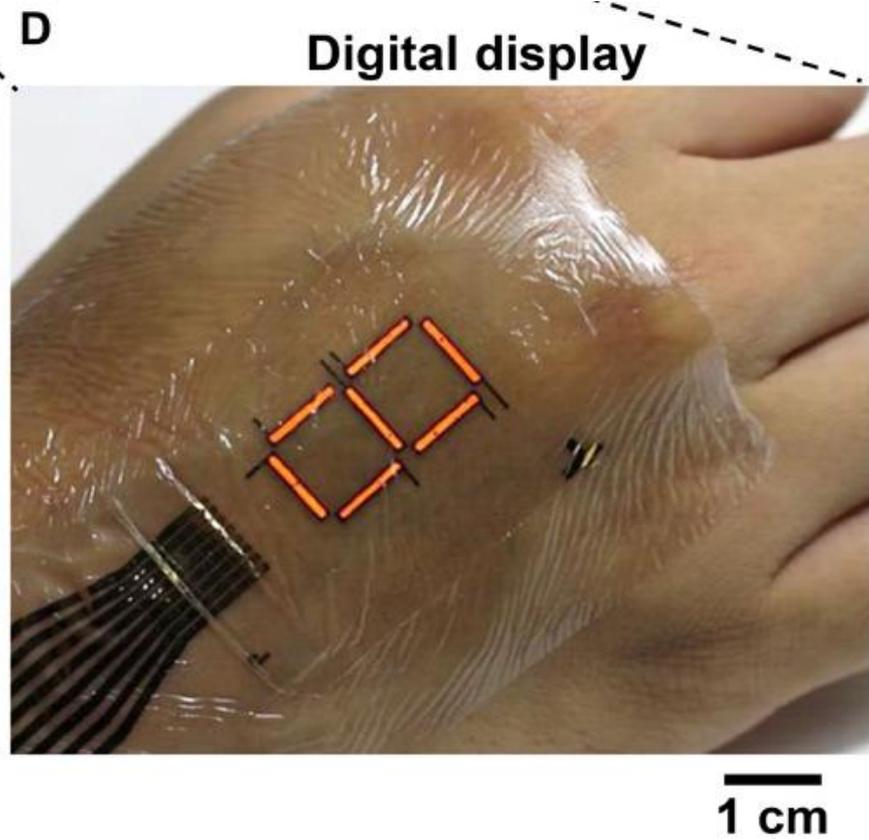
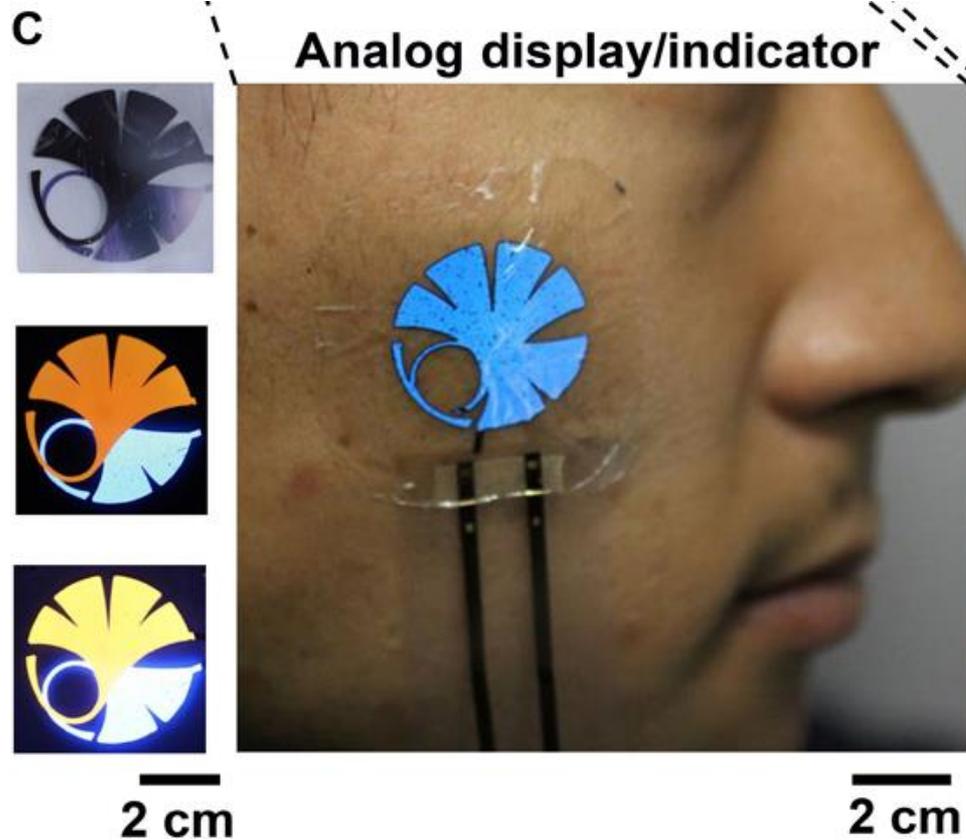
[6] Kaltenbrunner, *et al.*, *Nature* **499**, 458–463 (2013).  
<https://www.youtube.com/watch?v=y-kyN1-crCI>





# ORGANIC DISPLAYS

6



[3] Yokota, *et al.*, *Science Advances*, 2, 4 (2016).  
<https://www.youtube.com/watch?v=sixMVCYALmM>

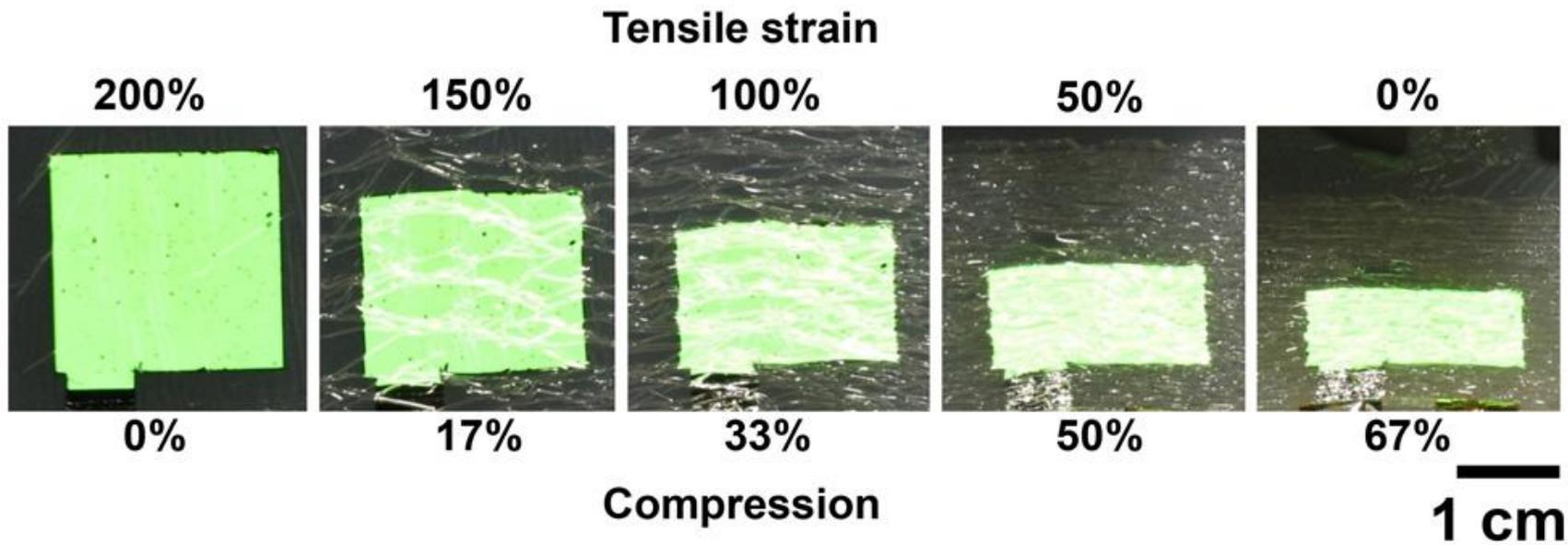




# ORGANIC DISPLAYS

7

A



[3] Yokota, *et al.*, *Science Advances*, 2, 4 (2016).



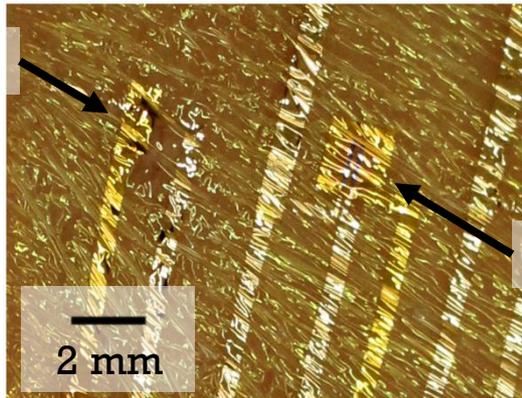


# 300 nm THIN ELECTRONICS

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- ▶ I (2016) fabricated imperceptible electronics that are < 300 nm thick<sup>7</sup>
- ▶ Ultra-flexible (bent 100x)
- ▶ Ultra-conformable ( $\sim 1.5 \mu\text{m}$ )
- ▶ Ultra-light ( $< 0.7 \text{ g m}^{-2}$ )
- ▶ Bio-compatible ( $> 10 \text{ hrs}$ )

Capacitor



OFET



[7] Nawrocki, *et al.*, *Adv. Ele. Mater.* **1500452**, (2016).

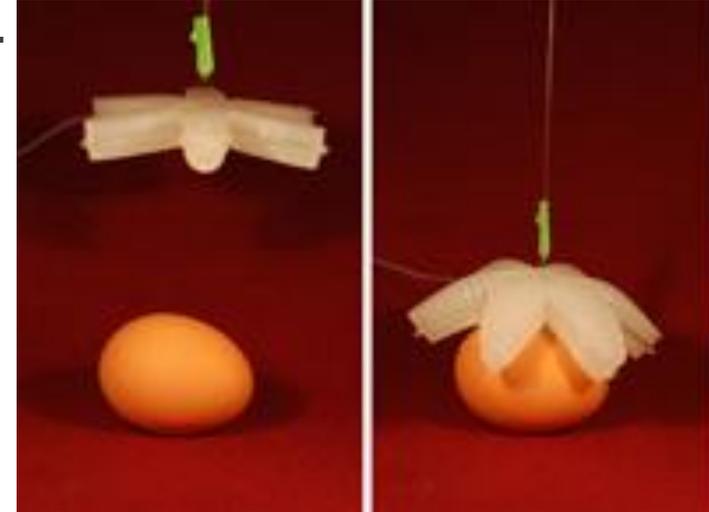




# SOFT ROBOTICS

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- Highly compliant materials, similar to those found in living organisms
- Draws heavily from the way in which living organisms move and adapt to their surroundings
- Allow for increased flexibility and adaptability for accomplishing tasks, and improved safety when working around humans
- Potential use in the fields of medicine and manufacturing



\* Courtesy of George Whitesides from Harvard  
<https://www.youtube.com/watch?v=2DsbS9cMOAE>





# PhD POSITION: OPENING

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- PhD position
  - Preferably with MS
  - Experience in:
    - Fabrication
    - And/Or
    - Electrical Computer Eng
- Postdoc (with own funding)
- Great school
- Great project
- Contact me:



**robertnawrocki@purdue.edu**



**THANK YOU**

